A2

Mechanically Soft Micro and Macrocomposite for Wearable Devices

Rainer Adelung & Tayebeh Ameri

biomagnetic sensing SFB 1261

Motivation and Objectives

Challenge 1: Reduction of intrinsic electric and magnetic noise sources in ME sensors

Reduction of sensor components to elementary magnetic/electric fields

Magnetic field:
- Permanent magnets

Electric field:
- Permanent, self-polarized electrets
- Real charge electrets

Challenge 2: A2 sensor currently only available on lab scale

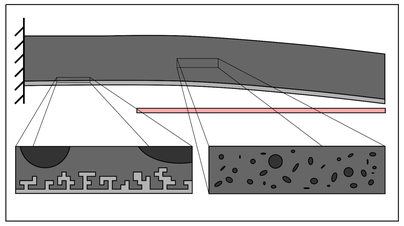
=> Sensors implemented into flexible, organic ME sensors for wearable application

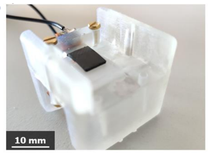
New approach: Combine previous materials and concepts to realize composite device with advantages of each component

Main objectives: Fundamentals, fabrication & characterization of flexible and integrated sensor systems
Transfer from lab individual devices to real medical application environment

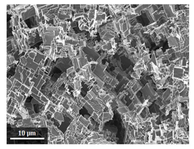
Results of the Second Funding Period

Sensor type 1: Microscopic sensor





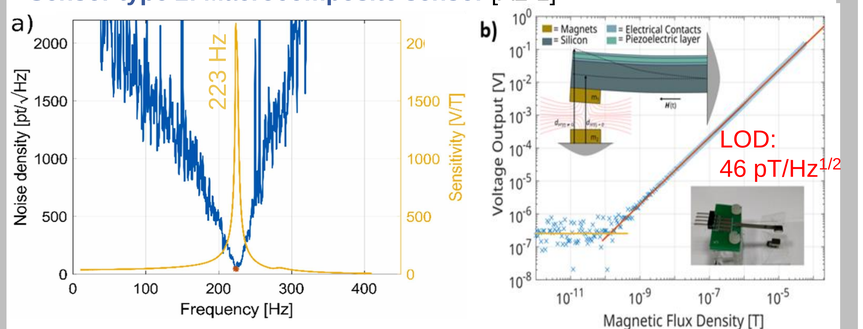
Customized sensor platform



Structured Al interlocking agent

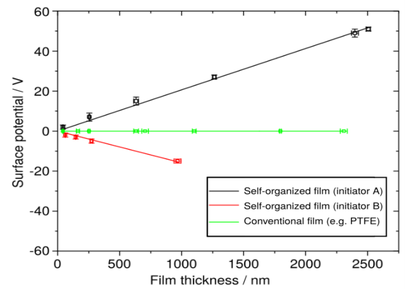
[A2-2, A2-4, A2-5]

Sensor type 2: Macrocomposite sensor [A2-1]



Electrets and soft conductors

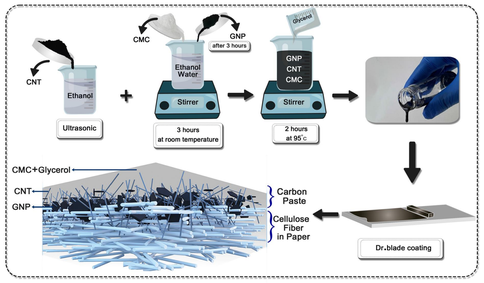
- Electrets via (iCVD) to reduce electret-based noise (e.g. burst noise)
- Naturally polarized iCVD polymer films with permanent potential
- Soft conductors based on iCVD coated AeroPEDOT:PSS [A2-03]

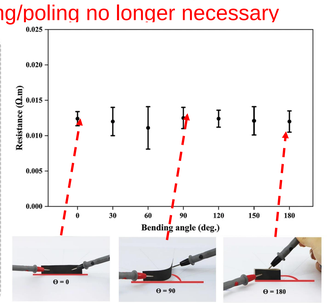


Printed electronics

[A2-06, A2-07, A2-09, A2-10]

Example: Self-polarized polymer films – Charging/poling no longer necessary





Example: Flexible carbon paste films [A2-08]

Work Plan for Third Funding Period

Research methods

Fabrication of ME sensor medical system: additive and substrative 3D manufacturing and iCVD

Encapsulation: EMI, iCVD

Characterization: FTIR, XPS, Kelvin-Probe AFM, TSD, Custom adoptable ME Setup

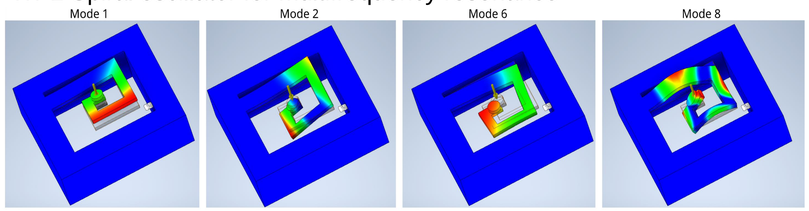
Modeling and sensor design: FEM (**A10**)

Work plan

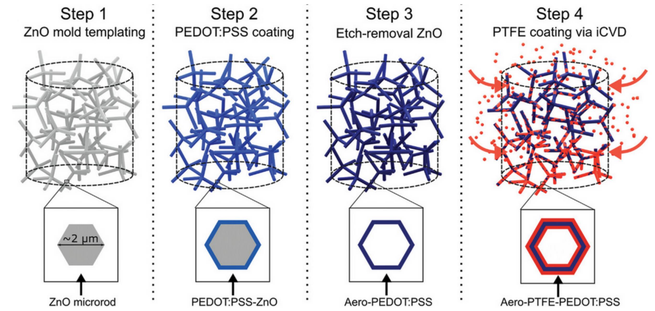
WP1 Micro- and macrocomposite magnetic sensors

Macro: two permanent magnets
Micro: microparticles in polymer matrix

WP2 Spiral oscillator for multifrequency resonance

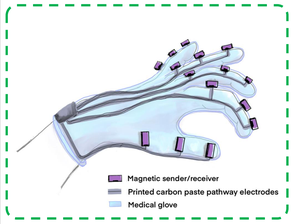


WP3 Soft electrodes and flexible conducting tracks

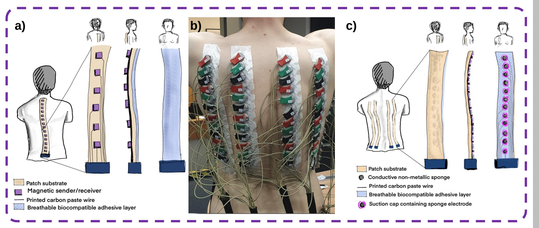


Example: PEDOT:PSS-PTFE strain-invariant soft electrodes

WP4 Wearable devices I



WP5 Wearable devices II



WP6 Device System assemblies and encapsulation

		2016		2017				2018				2019				2020	
		3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2
WP 1	Physical models																
WP 2	Parameters: functional layers																
WP 3	Sensor design																
WP 4	Fabrication & characterization																
WP 5	Evaluation & comparison																

Collaborations

A6: Microstructural characterization
A10: Simulation of composites
B9: Support for the movement
B10: Exchange on implantable devices, develop on ECG patch
B11(N): Development of positioning system using a self-powered transmitter
Z1: Powder magnets, Z1 provides cantilevers used in WP1
Z2: Magnetic characterization

Participation in focus groups
F3: Comparison of Sensor concepts
F4: Magnetoelectric Sensors

Funds Requested

2 Doctoral researcher, consumables: 64 k€

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